# **Temposonics**®



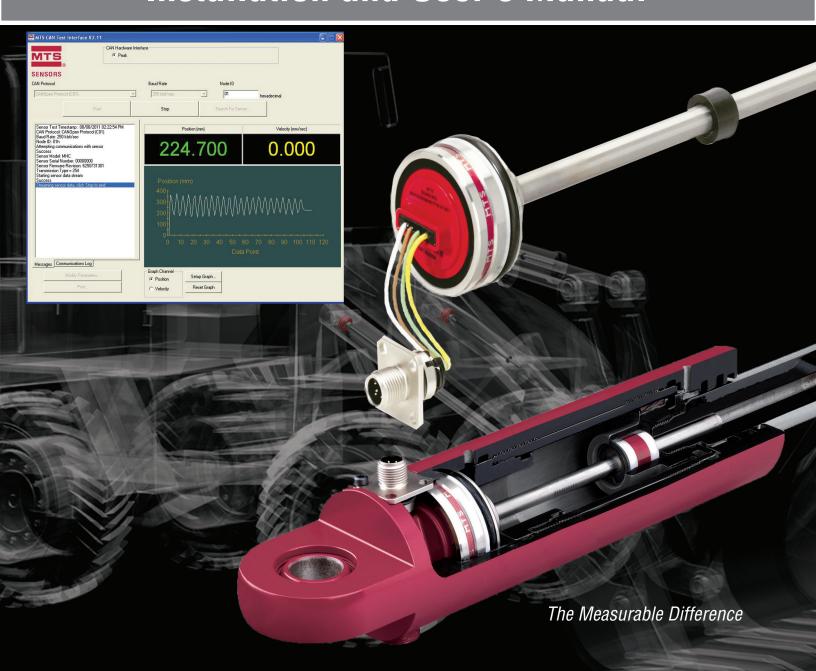
Magnetostrictive, Absolute, Non-contact Linear-Position Sensors

MH-Series Model MH Mobile Hydraulic Sensor CAN Test Kit

CANopen, CAN Safety and CAN J1939 Outputs

Document Part Number 551140 Revision B

# Installation and User's Manual



# MH-Series CAN Test Kit, CAN J1939, CANOpen and CAN Safety Table of Contents. Contact Information

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#### **Quote and Contract Terms & Conditions:**

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#### **Related Publications:**

MH-Series CAN Test kit Interface Data Sheet MTS part no. 551141 is available in PDF format at http://www.mtssensors.com.

# MH-Series CAN Test Kit, CAN J1939, CANOpen and CAN Safety Contents and USB-CAN Adapter Driver Installation

#### 1.0 MH-SERIES CAN TEST KIT

#### 1.1 Kit contents

The MH-Series CAN Test Kit includes:

- · USB CAN adapter kit:
  - · USB-CAN adapter
  - Utility CD (inclusive manual and drivers)
- . M12 test cable with DB9 connector
- · Pigtailed test cable with DB9 connector
- Multi-plug 12 Vdc power supply cable with power plug adapters
- . MTS CAN Test Interface installation CD
- · Carrying case
- CAN Test Interface Installation Manual/User's Guide

#### 2.0 INSTALLATION

#### Note:

This software must be installed on a PC using Windows 2000 or higher.

# 2.1 Installing USB-CAN adapter drivers software

- 1. Insert the 'USB-CAN Adapter Utility CD' into the CD drive.
- 2. Close the CD drive and wait for the installation program to begin.

#### Notes:

If the installation program does not start automatically, use the Windows explore function and browse to the appropriate drive and path of the USB-CAN adapter Utility drivers directory, then double-click 'Setup.exe' to start the installation. Wait for the prompt to disconnect all USB-CAN adapters.

3. The 'Welcome Screen/Language Select' window opens.



4. Select the desired language button to continue.

5. The 'Main Menu' window opens.



- 6. Select the 'Drivers' button to continue.
- 7. The 'Drivers' window opens.
- 8. Select 'PCAN-USB' to continue.
- 9. The 'Installation Wizard' window opens.



- 10. Click 'Next' to continue.
- 11. The 'License Agreement' window opens.



12. Select 'I agree to accept the license agreement' and click 'Next'.

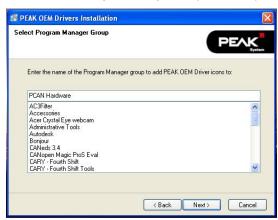
13. The 'Destination Directory' window opens.



- 14. If desired, use the 'Browse...' button to change the destination directory, or accept the default and select '**Next**'.
- 15. The 'Select Components' window opens.

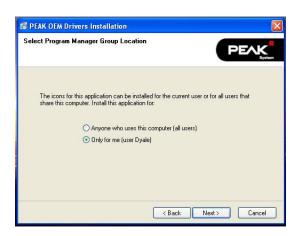


- Select 'PCAN-USB Driver' and 'PCAN-Dongle Driver' and click 'Nevt'
- 17. The 'Select Program Manager Group' window opens.

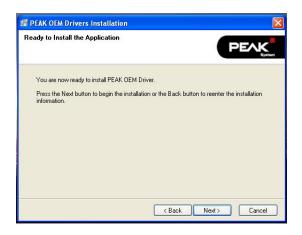


18. If desired, change the Program Manager group, or accept the default and click 'Next'.

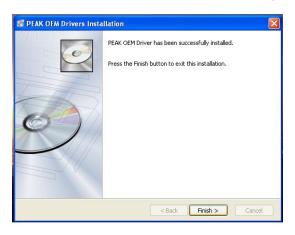
19. The 'Select Program Manage Group Location' window opens.



- 20. Select which user(s) will have access and click 'Next'.
- 21. The 'Ready to Install' window opens.



- 22. Click 'Next' to continue the installation.
- 23. Click 'Finish' to exit once the installation is complete.



# MH-Series CAN Test Kit, CAN J1939, CANOpen and CAN Safety USB-CAN Test Software Installation, Sensor Connections

#### 2.2 Installing the CAN test software

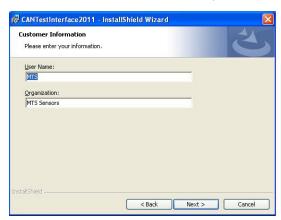
- 1. Insert the MH-Series CAN Test software CD into the CD tray.
- Close the CD tray and wait for the 'InstallShield Wizard' to launch.
- 3. When the 'InstallShield Wizard' opens, click 'Next'.



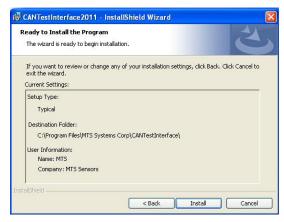
4. The 'License Agreement' window opens.



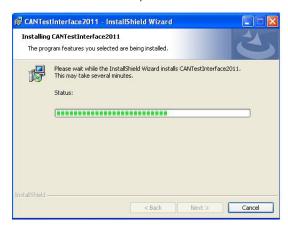
- Select 'I accept the terms in the license agreement' and click 'Nevt'
- 6. The 'Customer Information' window opens.



Click in each text box to enter the desired information and click 'Next'. 8. The 'Ready to Install the Program' window opens.



- Review the information and select 'Install' to continue with the installation. If any changes need to be made click 'Back'.
- 10. The 'Install' window opens.



- 11. When the installation is finished click 'Next'.
- 12. Click 'Finish' to exit once the installation is complete.

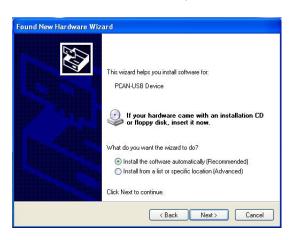
# 2.3 Connecting the USB-CAN adapter to the PC

- Plug the USB-CAN adapter into an empty USB port on your computer.
- 2. The 'Found New Hardware Wizard' window opens.

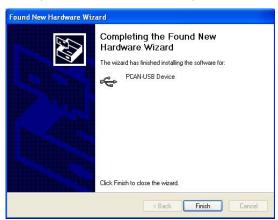


3. Select 'No, not this time' then, click 'Next' to continue.

4. The 'Install Software' window opens.



- Select 'Install the software automatically (Recommended)' and click 'Next'.
- 6. When the 'Completing the Found New Hardware Wizard' opens, click 'Finish'. This will complete the installation process.



# Note:

This process may need to be repeated if you use the USB-CAN adapter on another USB port on your computer.

# 2.4 CONNECTING THE SENSOR TO THE USB-CAN ADAPTER

# 2.4.1 Cable options for connecting the sensor

Choose one of the following two cable options below to connect your MH-Series sensor:

- For those cylinders and sensors that utilize the MTS M12 integrated connector system, use the M12 test cable with the DB9 connector end.
- For all other cylinders and sensors, use the 4-wire pigtailed test cable with the DB9 connector end cable. The desired mating connector can be field installed on the pigtails by the customer.

WIRE COLOR	CABLE PINOUT
Green	CAN Low
Yellow	CAN High
Brown	Power Supply
White	Ground

# 2.4.2 Connecting the sensor

- 1. Connect the female DB9 connector of the test cable to the male DB9 connector on the USB-CAN adapter.
- 2. Connect the other end of the cable to the sensor.
- 3. Connect the barrel connector of the AC adapter to the DC power receptacle hanging from the DB9 shell on the test cable.
- 4. Plug in the 12 Vdc power supply.

#### 2.5 REGISTERING THE SOFTWARE

### 2.5.1 Obtaining the unlock code

1. When the MH-Series CAN Test software is opened the first time, the following window opens:



- 2. The system identifier code can be E-mailed to Sensorsinfo@mts.com.
- A software key will be sent back. Enter this code in the 'Software Key'window and click 'Apply Key'. The software is now ready for use.

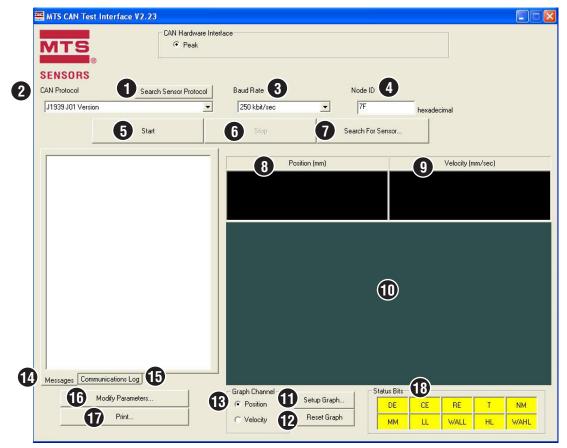
# MH-Series CAN Test Kit, CAN J1939, CANOpen and CAN Safety USB-CAN Test Interface Operation

#### 3.0 OPERATION

#### 3.1 Startup

Double-click the desktop icon to start the CAN Test Interface software. The MTS CAN Test Interface window opens.

# 3.2 Familiarizing yourself with the GUI



#### 1. Search Sensor Protocol

Automatically detects sensor CAN protocol.

#### 2. CAN Protocol

Allows manual selection of specific CAN protocol.

#### 3. Baud Rate

Allows selection of sensor baud rate.

#### 4. Node ID

Allows selection of sensor node ID.

# 5. Start

Initializes sensor output display.

# 6. Stop

Stops the display of sensor data.

# 7. Search For Sensor

Allows selective or auto search of the sensor.

# 8. Position Display

Displays the sensor output position in mm.

# 9. Velocity Display

Displays the magnet velocity in mm/sec.

# 10. Graphical Display

Displays a running measurement of position or velocity output.

#### 11. Setup Graph

Allows the user to set Y-Axis Maximum, Y-Axis Minimum, and the buffer size of the graphing window.

# 12. Reset Graph

Allows the user to reset the graph to default Y-Axis and buffer settings, and clears the data buffer.

# 13. Graph Channel

Selects either position or velocity data to display in the graph.

# 14. Messages

Displays user messages regarding the sensor and software communication.

# 15. Communication Log

Displays the raw CAN messages between the CAN Test Software and the sensor.

#### 16. Modify Parameters

Allows the user to program the sensor node ID, baud rate, and cycle time.

# 17. Print

Print the contents of the active message window.

# 18. Status Bits

Visual display of the sensor status register when available.

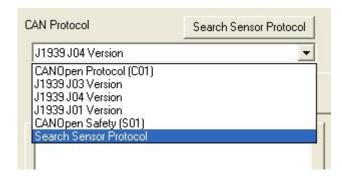
#### 3.3 INPUT SENSOR PARAMETERS

### 3.3.1 Selecting the sensor protocol

- 1. If the sensor protocol is known, click the down arrow on the CAN Protocol Menu (see [2] on page 6).
- Use the mouse to select the desired protocol and click to activate it.
- 3. If the protocol is unknown, press the 'Search Sensor Protocol' button (see [1] on page 6).

#### Note:

The software will provide the option to search for the sensor once the protocol is determined – see '3.4 Sensor Search'.

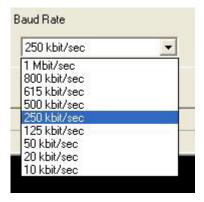


# 3.3.2 Selecting the sensor baud rate

- Click the down arrow on the Baud Rate Menu (see [3] on page 6).
   The drop down menu will display all available baud rates for the selected protocol.
- Use the mouse to select and click the appropriate baud rate to activate your selection.

# Note:

The baud rate must match the sensor baud rate or the CAN Test software will not communicate with the sensor.



#### 3.3.3 Input sensor node ID

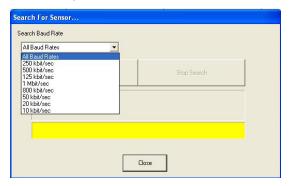
- 1. Click the mouse cursor inside the **node ID box** (see [4] on page 6).
- Enter the desired node ID. Note: the last 2 digits of the sensor model number are the node ID.



#### 3.4 SENSOR SEARCH

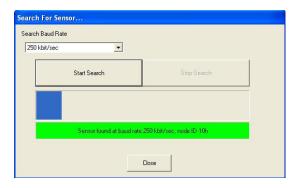
The steps in the previous section assume that the user knows the node ID and baud rate settings of the sensor. If these values are not known, the user can use the *'Search for Sensor'* function to determine the configuration of the sensor under test.

- 1. Click the 'Search for Sensor' button (see [7] on page 6).
- Click the down arrow to display Baud Rate selections. The drop-down menu will display all available baud rates for the selected protocol.
- 3. Use the mouse to select the desired baud rate and click to activate your selection. If the baud rate is not known select 'All



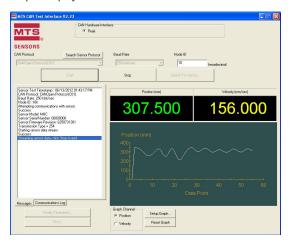
4. Click 'Start Search' to begin searching. When the software locates and displays the MH-Series sensor click 'Close'.

# MH-Series CAN Test Kit, CAN J1939, CANOpen and CAN Safety USB-CAN Test Interface Operation



### 3.5 START TEST

Click 'Start Test' button (see [5] on page 6) to initialize the sensor output display on the CAN Test Interface.



# 3.6 COMMUNICATION WINDOW

The communication window displays both summary and raw communications with the sensor.

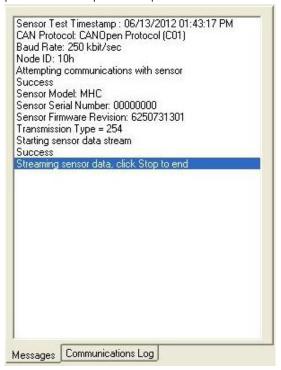
# 3.6.1 Messages Tab

The messages tab is displayed in the communications window by default and displays summary data of the attached sensor. If the messages tab is not displayed, click the 'Messages' tab (see [14] on page 6).

# Information that is displayed includes:

- · Timestamp of test
- · CAN protocol selected
- · Bauds rate
- Node ID
- · Communications verification
- · Sensor serial number
- · Sensor firmware revision
- · Data transfer verification

To print a record of the displayed information, click '**Print**' button (see [17] on page 6) below the communications window. A local printer or network printer is required.

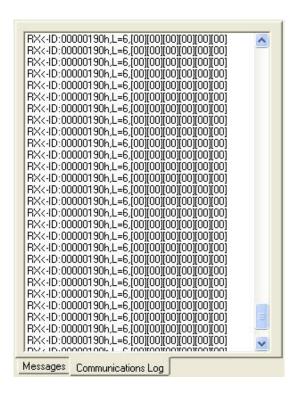


### 3.6.2 Communications Log Tab

The communications log tab displays the raw communications data between the CAN Test Interface and the attached sensor. To view the log, click the 'Communications Log' tab (see [15] on page 6).

#### Note:

Under normal use this information will not be needed. This is made available for advanced users and for troubleshooting with the factory.



The 'Print' button can also be used to print a record of this screen.

# 3.7 GRAPHING WINDOW

The 'graphing' window (see [10] on page 6) displays a rolling display of the sensor output data of the position display (see [8] on page 6) or the velocity display (see [9] on page 6).

# 3.7.1 Position/Velocity Selection

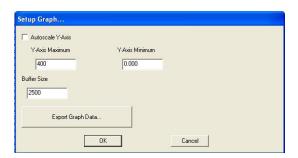
To view the graphical representation of the sensor output click the 'Position' or 'Velocity' radio button in the Graph Channel box (see [13] on page 6).



#### 3.7.2 Graphing Window Setup

To change the graph display settings:

- 1. Click the 'Setup Graph' button (see [11] on page 6).
- 2. To input fixed scaling for the Y-axis:
  - a. Uncheck the box next to 'Autoscale'.
  - b. Enter the desired *Y-axis* minimum and maximum values.
- 3. To return to Autoscale check the box next to 'Autoscale'.



1. The buffer size determines the maximum number of data points that will be displayed on the X-axis. When the buffer is full the oldest data will be discarded. The buffer size can be changed by clicking the 'Buffer Size' field and manually entering the desired value. Once the changes are made, click 'OK' to save the changes or 'Cancel' to return to the previous settings.

#### Note:

If a large buffer size is selected the graph may not be easily viewed on the screen as the buffer becomes full. If the graph becomes compressed [in the x-axis, reduce the buffer size until the graph rolls easily on the screen. Recommended buffer size is between 10 - 100,000.

#### 3.7.3 Reset Graph Settings

To revert back to the default settings click the 'Reset Graph' button (see [12] on page 6).

# 3.8 MODIFYING SENSOR SETTINGS

The CAN Test Interface can be used to modify the baud rate, cycle time, and node ID of the sensor.

#### 3.8.1 To modify the parameters:

Select the 'Modify Parameters' button (see [16] on page 6) to open the configuration screen.

# 3.8.2 Changing the sensor node ID:

- 1. Click inside the text box under 'Node ID' and enter the desired node ID for the sensor. The value must be hexadecimal. The valid ranges for each protocol are:
  - a. C01: 01 through 7F
  - b. S01: 01 through 40
  - c. J01: 01 through FD
  - d. J03: 01 through FF
  - e. J04: 01 through FF
- 2. Click the 'Write' button below the 'Baud Rate' text box to download the new node ID to the sensor

#### 3.8.3 Changing the baud rate:

- Click the down arrow on the 'Baud Rate' menu. The drop down menu will display all available baud rates for the selected protocol.
- 2. Use the mouse to select and click the desired 'Baud Rate'.

# MH-Series CAN Test Kit, CAN J1939, CANOpen and CAN Safety Contents and USB-CAN Adapter Driver Installation

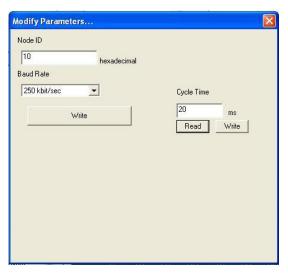
3. Click the 'Write' button below the 'Baud Rate' text box to download the new baud rate to the sensor.

# 3.8.4 Reading the cycle time:

Click the '**Read**' button below the 'Cycle Time' text box to display the current cycle time.

# 3.8.5 Changing the cycle time:

- 1. Click inside the text box below 'Cycle Time' and enter the desired value. The valid range is 1 ms to 65,535 ms.
- 2. Click the 'Write' button below the 'Baud Rate' text box to download the new cycle time to the sensor.



# 3.9 STATUS BITS

The status bit display (see **[18]** on page 6) can be used for trouble-shooting. Contact the factory for more information.

# 3.10 STOP TEST

Click the 'Stop Test' button (see [6] on page 6) to stop communication between the sensor and the CAN Test Software.

